



Verification of Real-Time Systems

Foundations of Abstract Interpretation

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Applications of Abstract Interpretation

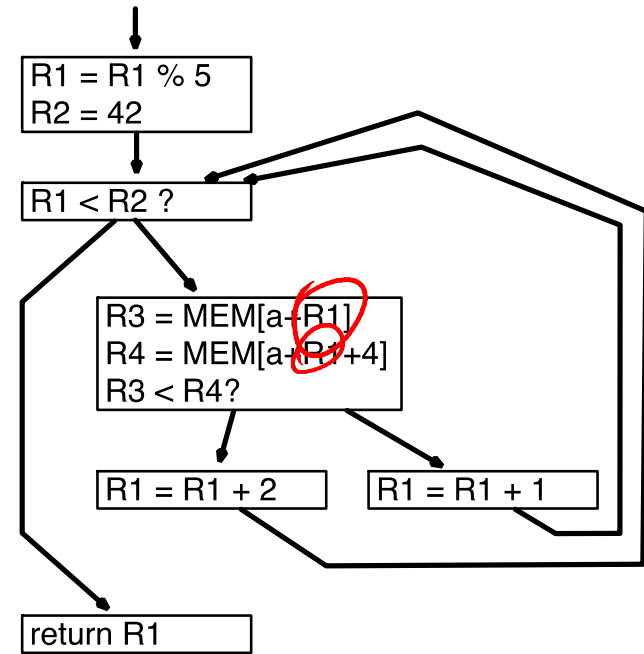
- Compilers:
 - Is it safe to perform a certain program transformation?
- Verification:
 - Can there be runtime errors? E.g. array out-of-bounds access, division-by-zero, dereferencing of null pointers
 - Security analysis: does information about secrets leak?
 - Timing analysis: loop bounds, cache analysis,...

Recap: Value Analysis

Determines **invariants on values of registers** at different program points. Invariants are often in the form of **enclosing intervals** of all possible values.

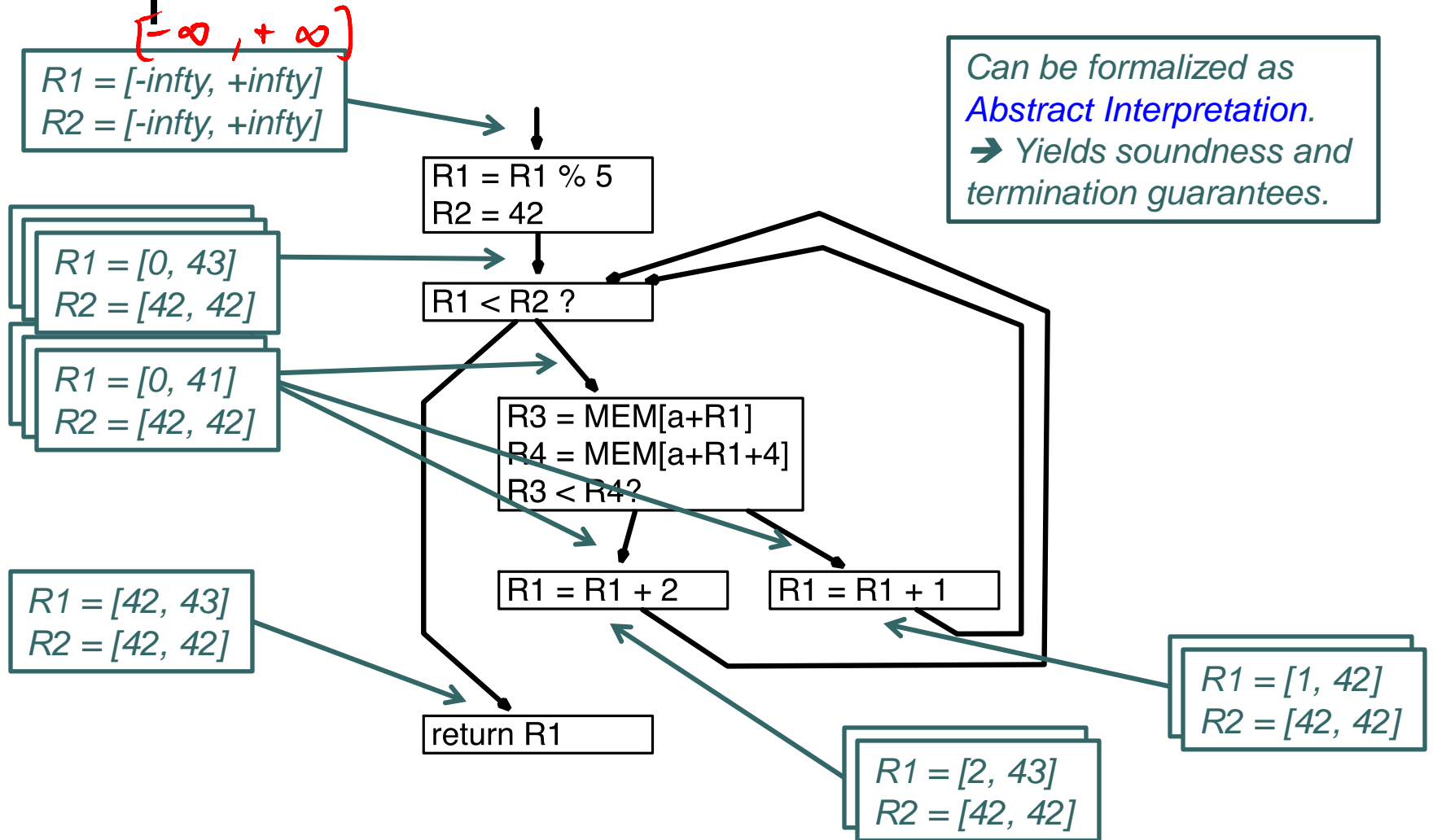
Where is this information used?

- Microarchitectural Analysis
 - Pipeline Analysis
 - Cache Analysis
- Control-Flow Analysis
 - Detect infeasible paths
 - Derive loop bounds



Value Analysis

Intuition of Interval Analysis





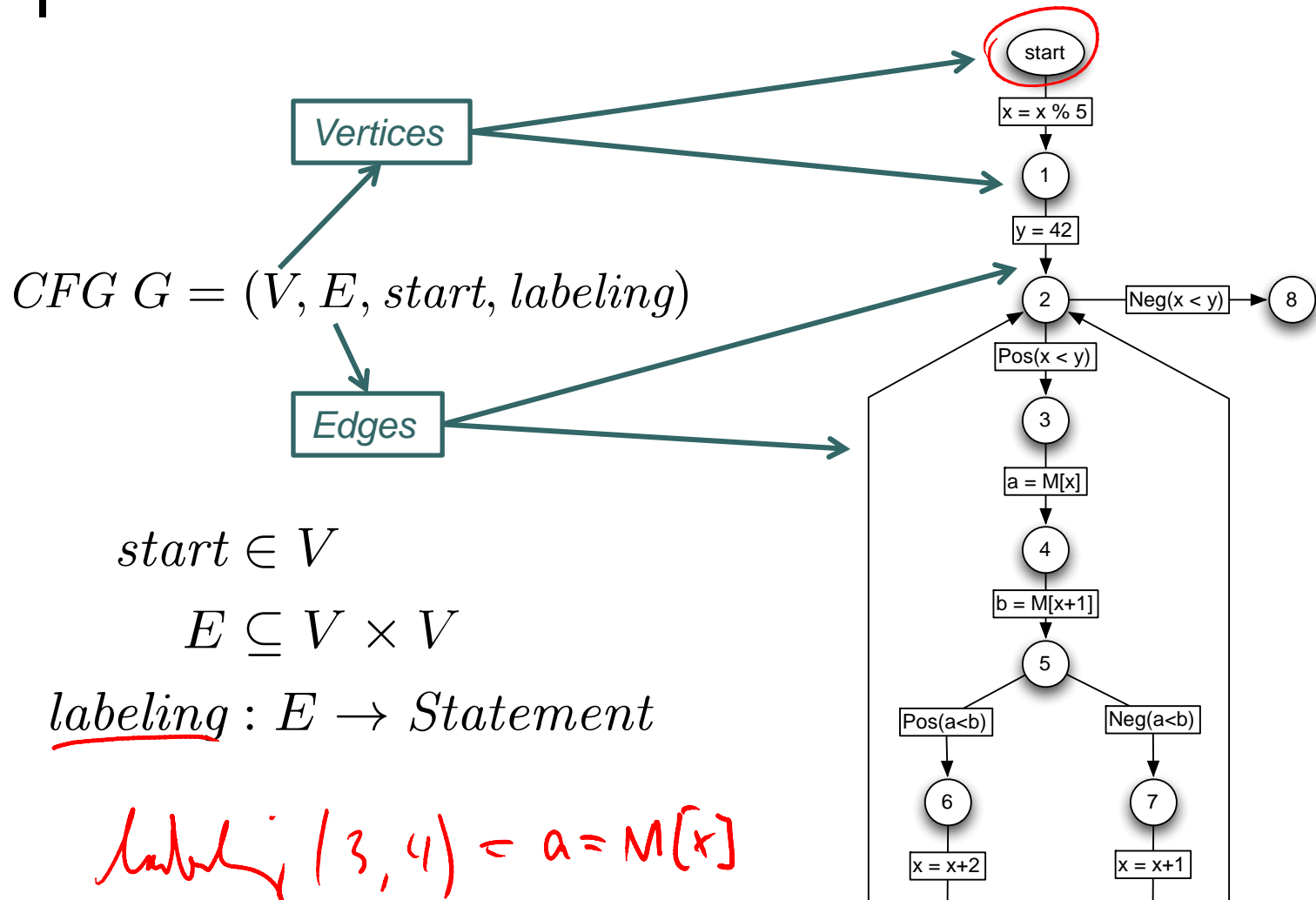
Abstract Interpretation

- Semantics-based approach to program analysis
- Framework to develop provably correct and terminating analyses

Ingredients:

- Concrete semantics: Formalizes meaning of a program
- Abstract semantics
- Both semantics defined as fixpoints of monotone functions over some domain
- Relation between the two semantics establishing correctness

Representing Programs by Control-Flow Graphs





Four Kinds of Statements

1. Assignment: $R = e$
2. Load: $R = M[e]$
3. Store: $M[e_1] = e_2$ \mathcal{R}
4. Test: $\text{Pos}(e)$ or $\text{Neg}(e)$

$$e = x + y + \text{?}$$

Meaning of Statements

$$\rho' = \rho[R \mapsto x]$$

$$\rho'(R) = x \mid \forall R' \neq R: \rho'(R') = \rho(R')$$

States consists of variables and memory:

$$s = (\rho, \mu) \in \text{States}$$

$$\rho : \text{Vars} \rightarrow \text{int}$$

Values of Variables

$$\mu : \mathbb{N} \rightarrow \text{int}$$

Contents of Memory

*Execution of a statement **transforms** states:*

$$\llbracket \text{statement} \rrbracket \subseteq \text{States} \times \text{States}$$

$$\llbracket R = e \rrbracket := \{((\rho, \mu), (\rho[R \mapsto \llbracket e \rrbracket \rho], \mu)) \mid (\rho, \mu) \in \text{States}\}$$

$$\llbracket R = M[e] \rrbracket := \{((\rho, \mu), (\rho[R \mapsto \mu(\llbracket e \rrbracket \rho)], \mu)) \mid (\rho, \mu) \in \text{States}\}$$

$$\llbracket M[e_1] = e_2 \rrbracket := \{((\rho, \mu), (\rho, \mu[\llbracket e_1 \rrbracket \rho \mapsto \llbracket e_2 \rrbracket \rho])) \mid (\rho, \mu) \in \text{States}\}$$

$$\llbracket \text{Pos}(e) \rrbracket := \{((\rho, \mu), (\rho, \mu)) \mid (\rho, \mu) \in \text{States} \wedge \llbracket e \rrbracket \rho \neq 0\}$$

$$\llbracket \text{Neg}(e) \rrbracket := \{((\rho, \mu), (\rho, \mu)) \mid (\rho, \mu) \in \text{States} \wedge \llbracket e \rrbracket \rho = 0\}$$



Meaning of Expressions

Evaluation of expressions is as expected:

$$\llbracket a \rrbracket \rho := \rho(a) \qquad \text{if } a \in \text{Vars}$$

$$\llbracket e_1 \otimes e_2 \rrbracket \rho := \llbracket e_1 \rrbracket \rho \otimes \llbracket e_2 \rrbracket \rho$$

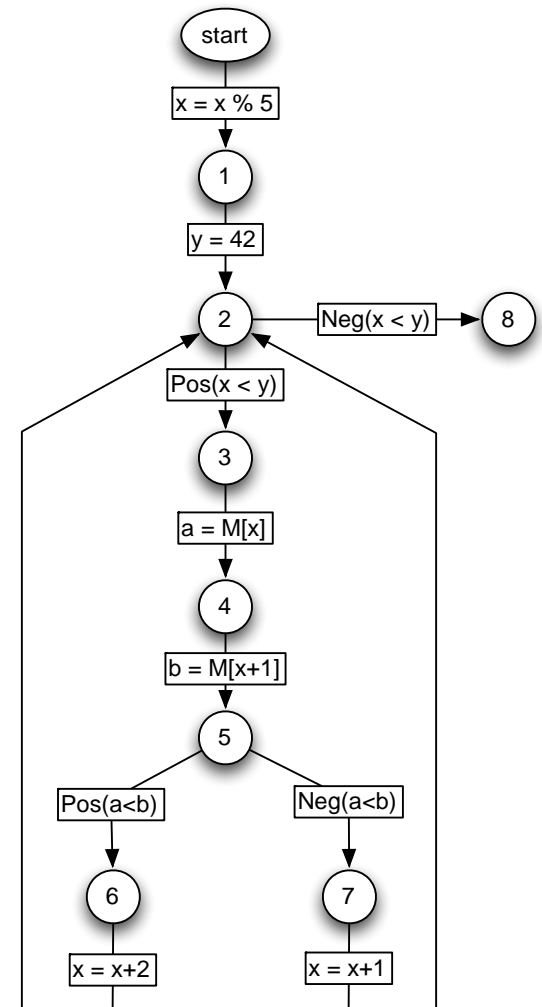
$$\llbracket a < b \rrbracket \rho := \begin{cases} 1 & : \llbracket a \rrbracket \rho < \llbracket b \rrbracket \rho \\ 0 & : \text{otherwise} \end{cases}$$

...

Concrete Semantics

Different **semantics** are required for different properties:

- “Is there an execution in which the value of x alternates between 3 and 5?” → **Trace Semantics**
- “Is the final value of x always the same as the initial value of x ?” → **“Input/Output” Semantics**
- “May x ever assume the value 45 at program point 7?” → **Reachability Semantics**





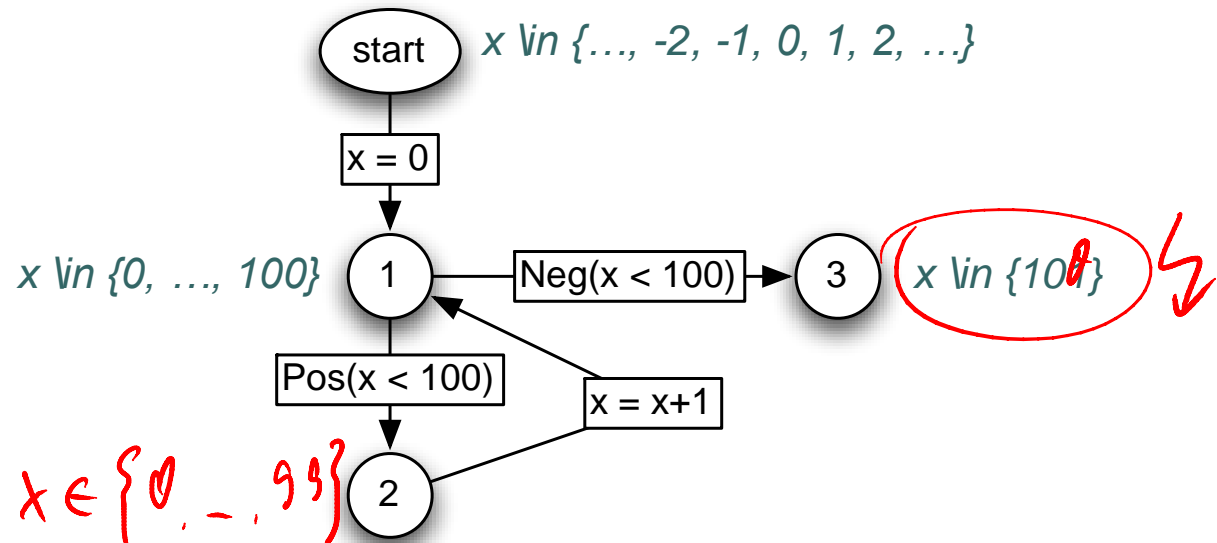
Concrete Semantics

- **Trace Semantics**: Captures set of traces of states that the program may execute.
- **Input/Output Semantics**: Captures the pairs of initial and final states of execution traces.
 - Abstraction of Trace Semantics
- **Reachability Semantics**: Captures the set of reachable states at each program point
 - Abstraction of Trace Semantics

Reachability Semantics

Captures the **set of reachable states at each program point**. Formally: $Reach : V \rightarrow \mathcal{P}(\text{States})$

Example:

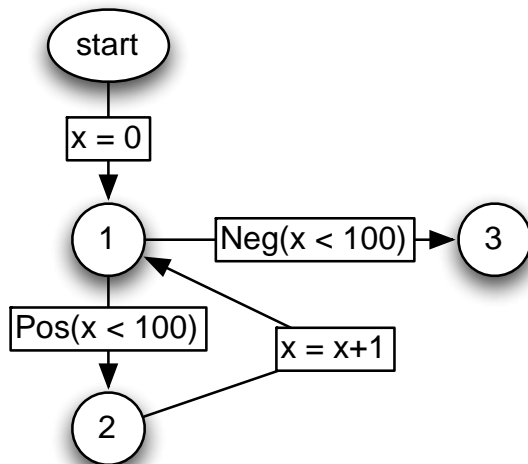


Reachability Semantics

Can be captured as the **least solution** of:

$$Reach(start) = \underline{States}$$

$$\forall v' \in V \setminus \{start\} : Reach(v') = \bigcup_{v \in V, (v, v') \in E} \llbracket labeling(v, v') \rrbracket (Reach(v))$$



$$Reach(1) = \llbracket labeling(start, 1) \rrbracket (Reach(start)) \cup \llbracket labeling(2, 1) \rrbracket (Reach(2))$$

$$Reach(2) = \llbracket labeling(1, 2) \rrbracket (Reach(1))$$

$$Reach(3) = \llbracket labeling(1, 3) \rrbracket (Reach(1))$$

$$Reach(1) = \llbracket x = 0 \rrbracket (Reach(start)) \cup \llbracket x = x + 1 \rrbracket (Reach(2))$$

$$Reach(2) = \llbracket Pos(x < 100) \rrbracket (Reach(1))$$

$$Reach(3) = \llbracket Neg(x < 100) \rrbracket (Reach(1))$$

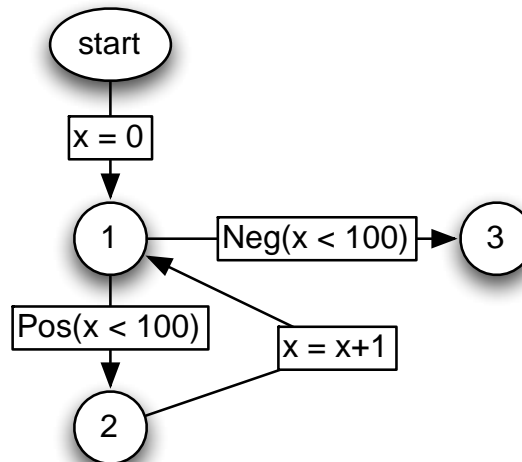
$$Reach(1) = \{0\} \cup \{v + 1 \mid v \in Reach(2)\}$$

$$Reach(2) = Reach(1) \cap \{\dots, 98, 99\}$$

$$Reach(3) = Reach(1) \cap \{100, 101, \dots\}$$

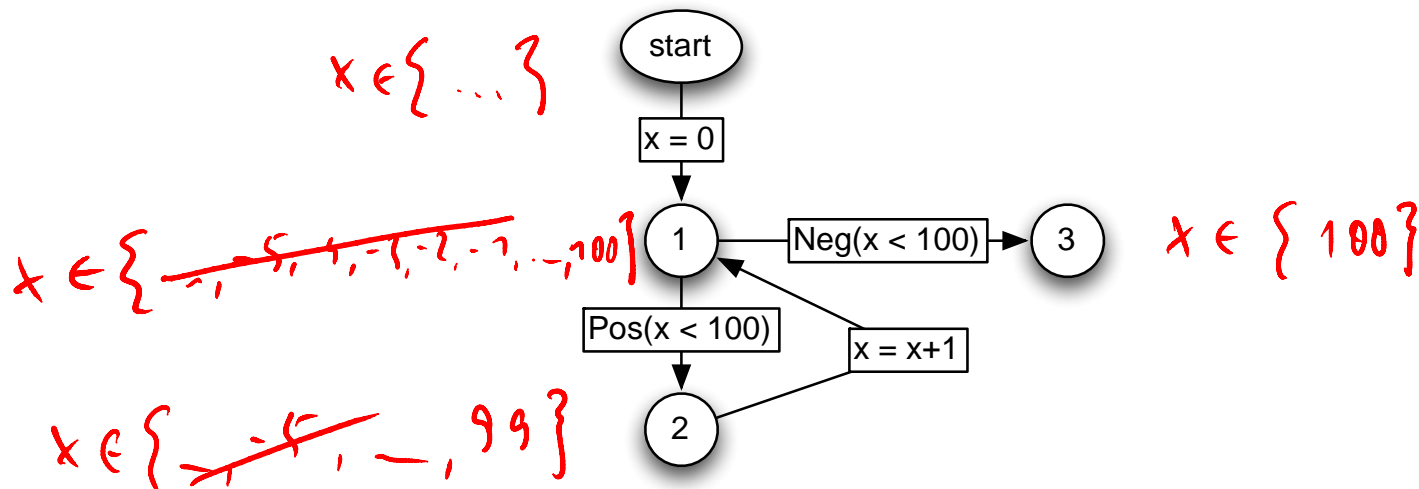
Questions

- Why the **least solution**?
- Is there more than one solution?
- Is there a **unique** least solution?
- Can we systematically compute it?



Answers

- Is there more than one solution? Yes!
- Is there a **unique** least solution? Yes!
- Can we systematically compute it? Yes and No.





Why? Knaster-Tarski Fixpoint Theorem!

THEOREM 1 (KNASTER-TARSKI, 1955).

Assume (D, \leq) is a complete lattice. Then every monotonic function $f : D \rightarrow D$ has a least fixed point $d_0 \in D$.

Raises more questions:

- What is a **complete lattice**?
- What is a **monotonic function**?
- What is a **fixed point**?

Monotone Functions

$$f: A \rightarrow B$$

Let (D, \leq) be *partially-ordered set*.

For example: $D = \mathbb{N}$ and \leq the order on natural numbers.

Function $f: D \rightarrow D$ is *monotone* (order-preserving) iff
for all $d_1, d_2 \in D : d_1 \leq d_2 \Rightarrow f(d_1) \leq f(d_2)$.

Examples:

$$f(x) = x$$

✓

$$d_1 \leq d_2 \Rightarrow d_1 \leq d_2$$

$$g(x) = -x$$

✗

$$h(x) = x - 1$$

✓

Which of these are monotone?

$(\mathcal{P}(\mathbb{N}), \subseteq)$

$$F(X) = \{f(x) \mid x \in X\}$$

$$G(X) = \{y \mid x \in X \wedge (x, y) \in R\}$$

Need to know what the order is.



Partial Orders

A binary relation \leq on $D \times D$ is a *partial order*, iff for all $a, b, c \in D$, we have that:

- $a \leq a$ (reflexivity),
- if $a \leq b$ and $b \leq a$ then $a = b$ (antisymmetry),
- if $a \leq b$ and $b \leq c$ then $a \leq c$ (transitivity).

A set with a partial order is called a partially-ordered set.



Partial Orders: Examples I

The natural numbers ordered by the standard less-than-or-equal relation: (\mathbb{N}, \leq) . (\mathbb{N}, \geq)

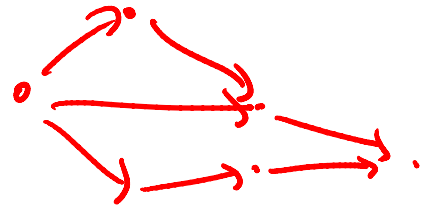
The set of subsets of a given set (its powerset) ordered by the subset relation: $(\mathcal{P}(A), \subseteq)$.

The set of subsets of a given set (its powerset) ordered by the subset relation: $(\mathcal{P}(A), \supseteq)$.

The natural numbers ordered by *divisibility*: $(\mathbb{N}, |)$.

$$3 \mid 9 \quad \neg(9 \mid 3) \quad \underline{\hspace{1cm}}$$

Partial Orders: Examples II



The vertex set V of a directed acyclic graph $G = (V, E)$ ordered by reachability (reflexive, transitive closure of edge relation).

~~The vertex set V of an arbitrary graph $G = (V, E)$ ordered by reachability.~~



For a set X and a partially-ordered set P , the function space $F : X \rightarrow P$, where $f \leq g$ if and only if $f(x) \leq g(x)$ for all x in X .

What about $\text{Reach} : \underline{V} \rightarrow \underline{\mathcal{P}(\text{States})}$?

$$f \leq g \iff \forall v \in V. f(v) \leq g(v)$$



Complete Lattices

A partially-ordered set (L, \leq) is a *complete lattice* if every subset A of L has both a *least upper bound* (denoted $\bigsqcup A$) and a *greatest lower bound* (denoted $\bigsqcap A$).

What is an upper bound of a set A ?

An element x is an upper bound of a set A if x if for every element a of A , we have $a \leq x$.

What is the least upper bound (also: join, supremum) of a set A ?

x is the *least upper bound* of A , denoted $\bigsqcup A$, if

1. x is an upper bound of A ,
2. for every upper bound y of A , we have $x \leq y$.